

Adaptive Prediction Sets with Class Conditional Coverage

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Summary

We introduce **CCAPS**: an algorithm which can **convert any black-box classifier** to output a predictive set of labels guaranteed to satisfy **class conditional coverage**.

CCAPS works regardless of how big the calibration set (**finite sample**), works on any dataset (**distribution-free**) can wrap around any model (**model-agnostic**) and is flexible enough to allow users to choose a subset of classes on which they want the coverage guarantees to hold.

Goal

Suppose we have a labeled dataset $\{(X_i, Y_i)\}_{i=1}^n$. Then, given an unseen example (X_{n+1}, Y_{n+1}) , we want to construct a set valued function $\hat{C}_{n,\alpha}: \mathcal{X} \rightarrow 2^{\mathcal{Y}}$ such that

$$\mathbb{P}[Y_{n+1} \in \hat{C}(X_{n+1}) | Y_{n+1} = y] > 1 - \alpha$$

holds. This is the **class-conditional coverage** guarantee.

Method

Algorithm 1 CCAPS (Class Conditional Adaptive Prediction Sets)

- 1: **Input:** dataset $\{(X_i, Y_i)\}_{i=1}^n$, new data point X_{n+1} , confidence level α , number of classes K , exclusion threshold $\gamma \in [0, K - 1]$
- 2: Split the training data into 2 subsets, $\mathcal{I}_{\text{train}}, \mathcal{I}_{\text{cal}}$
- 3: Split \mathcal{I}_{cal} into K disjoint subsets $\mathcal{I}_{\text{cal}}^{(1)}, \dots, \mathcal{I}_{\text{cal}}^{(K)}$, where $\mathcal{I}_{\text{cal}}^{(k)} = \{(X_i, Y_i) \in \mathcal{I}_{\text{cal}} \mid Y_i = k\}$
- 4: $\hat{\pi} \leftarrow$ black-box learning model trained on $\mathcal{I}_{\text{train}}$
- 5: **for** $k \in 1, \dots, K$ **do**
- 6: $E_i \leftarrow E(X_i, Y_i; \hat{\pi}), \forall (X_i, Y_i) \in \mathcal{I}_{\text{cal}}^{(k)}$ where E is defined in (6)
- 7: $\hat{\tau}_k \leftarrow$ the $[(1 - \alpha)(1 + |\mathcal{I}_{\text{cal}}^{(k)}|)]$ -th largest value in $\{E_i\}_{i \in \mathcal{I}_{\text{cal}}^{(k)}}$
- 8: **end for**
- 9: $\{\hat{\tau}_k\} \leftarrow \{\hat{\tau}_k\}$ excluding top γ largest $\hat{\tau}_k$
- 10: $\hat{\tau}_{\max} \leftarrow \max_k \{\hat{\tau}_k\}$
- 11: $\hat{C}_{n,\alpha}^{SC}(X_{n+1}) \leftarrow S(X_{n+1}; \hat{\pi}, \hat{\tau}_{\max})$
- 12: **Output:** The $1 - \alpha$ class-conditional prediction set $\hat{C}_{n,\alpha}^{SC}(X_{n+1})$ for unobserved label Y_{n+1}

Formal Guarantees

Theorem (CCAPS Coverage Guarantee). Let the data be denoted by $\{(X_i, Y_i)\}_{i=1}^n$. If the data is exchangeable and the black box learning algorithm utilized to train the model in Algorithm 1 is invariant to permutations of its input samples, the output of Algorithm 1 satisfies the following for each class $k \in \{1, \dots, K\}$:

$$\mathbb{P}[Y_{n+1} \in \hat{C}(X_{n+1}) | Y_{n+1} = k] > 1 - \alpha.$$

Experiments

Hyperparameters			Coverage		Min. CC		Set Size	
Dataset	# Calib	Method	APS	CCAPS	APS	CCAPS	APS	CCAPS
MNIST (C=10)	10K	RFC	0.90	0.96	0.79	0.90	1.49	2.12
MNIST (C=10)	10K	MLP	0.90	0.92	0.87	0.89	0.89	0.98
CIFAR10 (C=10)	10K	RFC	0.90	0.93	0.85	0.90	5.43	6.27
CIFAR10 (C=10)	10K	MLP	0.90	0.94	0.85	0.90	4.94	6.68
ImageNet (C=1K)	25K	RN-152	0.90	0.99	0.52	0.91	6.34	296.
CIFAR-10 (C=10)	5K	MLP	0.91	0.93	0.86	0.90	5.28	5.5
CIFAR-10 (C=10)	2.5K	MLP	0.90	0.94	0.85	0.90	4.26	5.00
CIFAR-10 (C=10)	1K	MLP	0.90	0.92	0.80	0.89	4.33	4.99
CIFAR10-LT (C=10)	10K	RFC	0.90	0.99	0.29	0.90	5.31	9.65

- Compared to APS by Romano et al., CCAPS achieves coverage **for every class** for experiments when $\alpha = 0.1$.
- CCAPS provides a **finite-sample guarantee**, working for an arbitrary calibration set size.

Applications and Future Steps

- Class-conditional coverage is an important metric in both healthcare, security, and other related risky fields where reliable uncertainty quantification is key.
- Our set sizes are currently large, so *approximate conditional coverage* as a weaker guarantee could be explored.