



# Improved Weak Gravitational Lensing Using Generative Adversarial Networks

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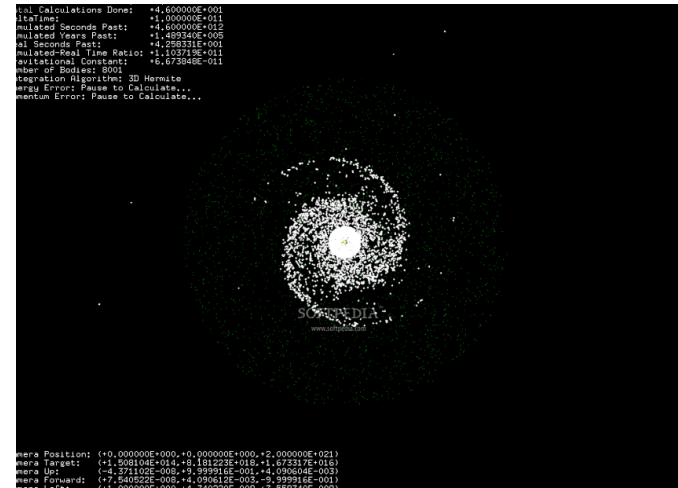
## Background

### Gravitational Lensing

- Gravitational lensing occurs when massive objects create gravitational fields that distort photon trajectories in space.
- Weak Gravitational Lensing (WGL) is a tool that acts as a tracer for dark matter and allows physicists to make predictions about cosmic acceleration.

### Problem

- Cosmological models known as N-body simulators are resource intensive as they track the movements of billions of particles through space.

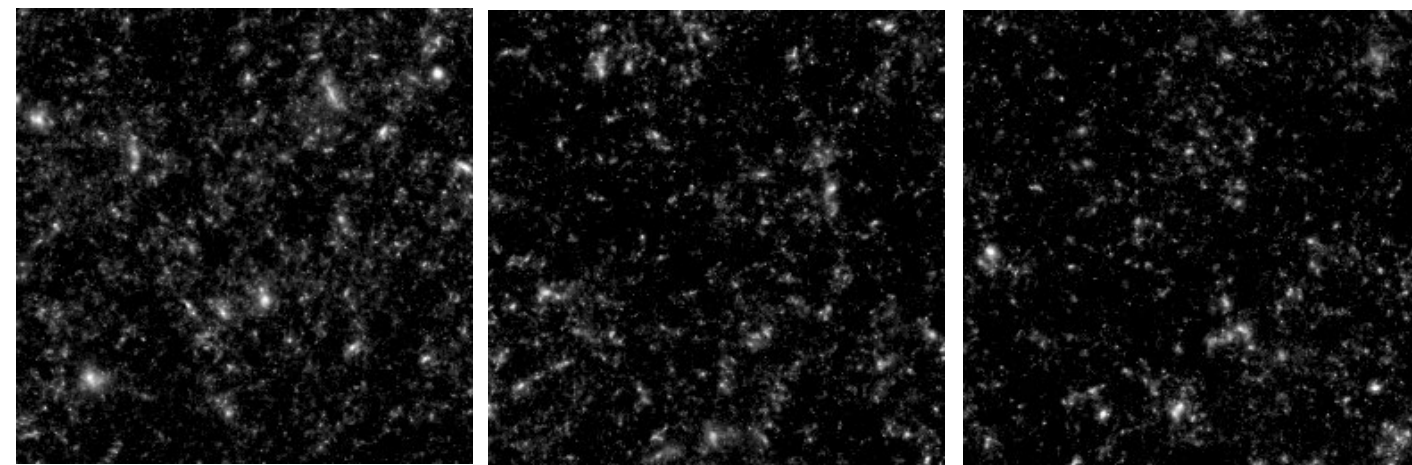


### Our Approach and Objectives

- Generative Adversarial Networks have achieved state of the art performance in cosmological modeling.
- Investigate ways to prevent mode collapse
- Goal:** To produce samples resembling baseline images with higher model stability.

## Data

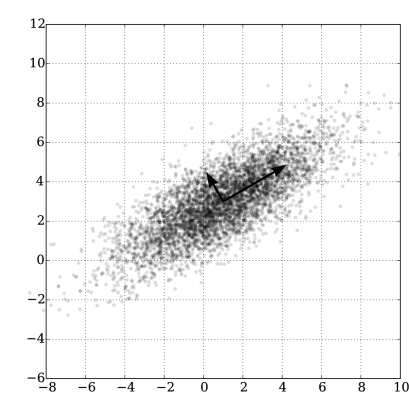
- 16,000 images (256 x 256) generated using Gadget2 [1] N-Body simulation code to create mock WL convergence maps.
- Sample validation from all maps because GAN's generator networks are not directly trained on the dataset but instead learn about it from the discriminator indirectly



Random sampled training data instances

## Metrics

- Pixel Intensity:** traditional first-order statistic used in cosmological imaging
- Power Spectrum:** measure of the correlation in gravitational lensing at different distances
- Convergence using Principal Components:** assess convergence quality by plotting generated images along the top two principal components and examining the shape compared to the validation set.



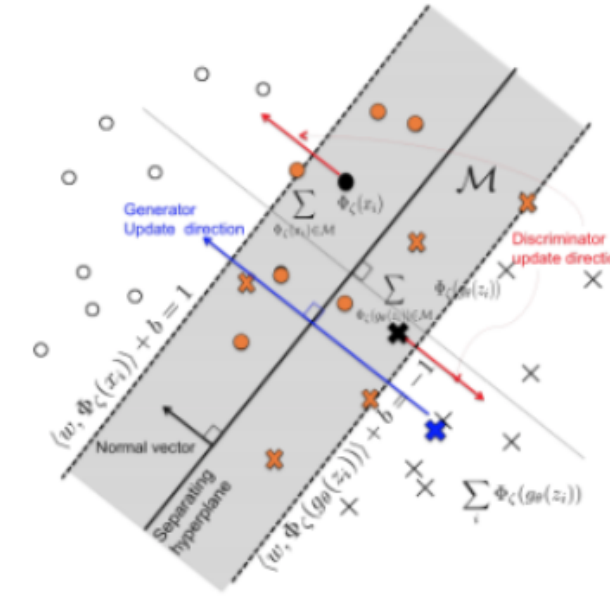
## Framework / Methods

### Method 1: Geometric GAN

- GeoGAN uses an SVM separating hyperplane, composed of the following operations in feature space

  - Finding a separating hyperplane for a linear classifier
  - Discriminator parameter update away from hyperplane using gradient descent.
  - Generator parameter update along direction normal to hyperplane.

- Mathematically proven to converge to a Nash equilibrium as training examples  $n \rightarrow \infty$



### Discriminator Loss

$$\frac{1}{2Cn} \sum_{i=1}^n \|w\|^2 + \frac{1}{n} \sum_{i=1}^n \max(0, 1 - \langle w, 1 - \Phi_C(z^{(i)}) - b \rangle) - \frac{1}{n} \sum_{i=1}^n \max(0, 1 - \langle w, 1 + \Phi_C(g_\theta(z^{(i)})) + b \rangle)$$

### Generator Loss

$$L_{w,b,c}(\theta) := -\frac{1}{n} \sum_{i=1}^n D_{w,b,c}(g_\theta(z_i))$$

### Optimization Problem

$$\min_{w,b} \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n (\xi_i + \xi_i')$$

$$\langle w, \Phi(x^{(i)}) \rangle + b \geq 1 - \xi_i, i = 1, \dots, n$$

$$\langle w, \Phi(x^{(i)}) \rangle + b \leq \xi_i' - 1, i = 1, \dots, n$$

$$\xi_i, \xi_i' \geq 0, i = 1, \dots, n$$

### Discriminator network architecture

layer types, activations, output shapes, and number of trainable parameters per layer. Note the inclusion of Minibatch discrimination to prevent mode collapse.

	Activ.	Output Shape	Params.
Input map	-	1 x 256 x 256	-
Conv 5 x 5	LReLU	64 x 128 x 218	1664
VirtualBatchNorm	LReLU	128 x 64 x 64	256
Conv 5 x 5	LReLU	256 x 32 x 32	819K
VirtualBatchNorm	LReLU	256 x 32 x 32	512
Conv 5 x 5	-	512 x 16 x 16	3.3M
VirtualBatchNorm	LReLU	512 x 16 x 16	1024
Minibatch Discrimination	-	256 x 256	256 <sup>2</sup>
Conv 5 x 5	LReLU	512 x 16 x 16	4.4M
Linear	ReLU	1	131K

### Method 3: Relativistic Discriminator

- Modification: the discriminator now estimates the probability that the real data is more realistic than randomly sampled fake images.

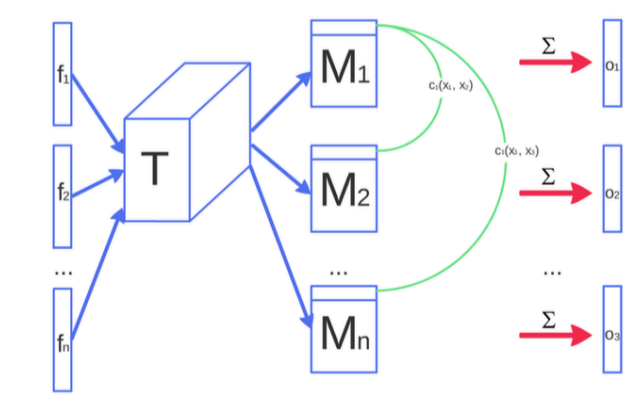
### Modified Discriminator Loss

$$\frac{1}{2Cn} \sum_{i=1}^n \|w\|^2 + \frac{1}{n} \sum_{i=1}^n \max(0, 1 - \langle w, 1 - \Phi_C(z^{(i)}) + \Phi_C(g_\theta(z^{(i)})) - b \rangle) + \frac{1}{n} \sum_{i=1}^n \max(0, 1 - \langle w, 1 + \Phi_C(g_\theta(z^{(i)}) - \Phi_C(z^{(i)})) + b \rangle)$$

### Method 2: Mini-batch discrimination

- Technique to reduce mode collapse. Incorporates the *closeness* of an image with the others in its batch and feeds this result into next layer of discriminator.

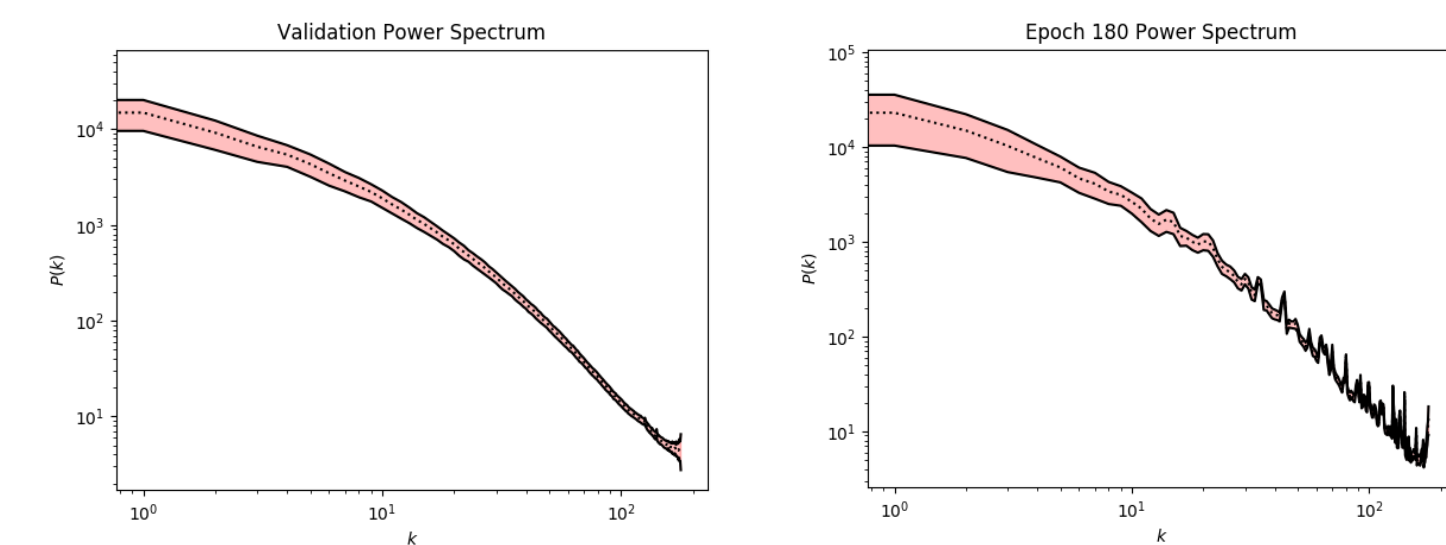
$$c_b(x_i, x_j) = \exp(-\|M_{i,b} - M_{j,b}\|_1)$$



	Activ.	Output Shape	Params.
Latent	-	64	-
Dense 5 x 5	-	512 x 16 x 16	8.5M
VirtualBatchNorm	ReLU	512 x 16 x 16	1024
TConv 5 x 5	-	256 x 32 x 32	3.3M
VirtualBatchNorm	ReLU	256 x 32 x 32	512
TConv 5 x 5	-	128 x 64 x 64	819K
VirtualBatchNorm	ReLU	128 x 64 x 64	256
TConv 5 x 5	-	64 x 128 x 128	205K
VirtualBatchNorm	ReLU	64 x 128 x 128	128
Conv 5 x 5	Tanh	1 x 256 x 256	1601

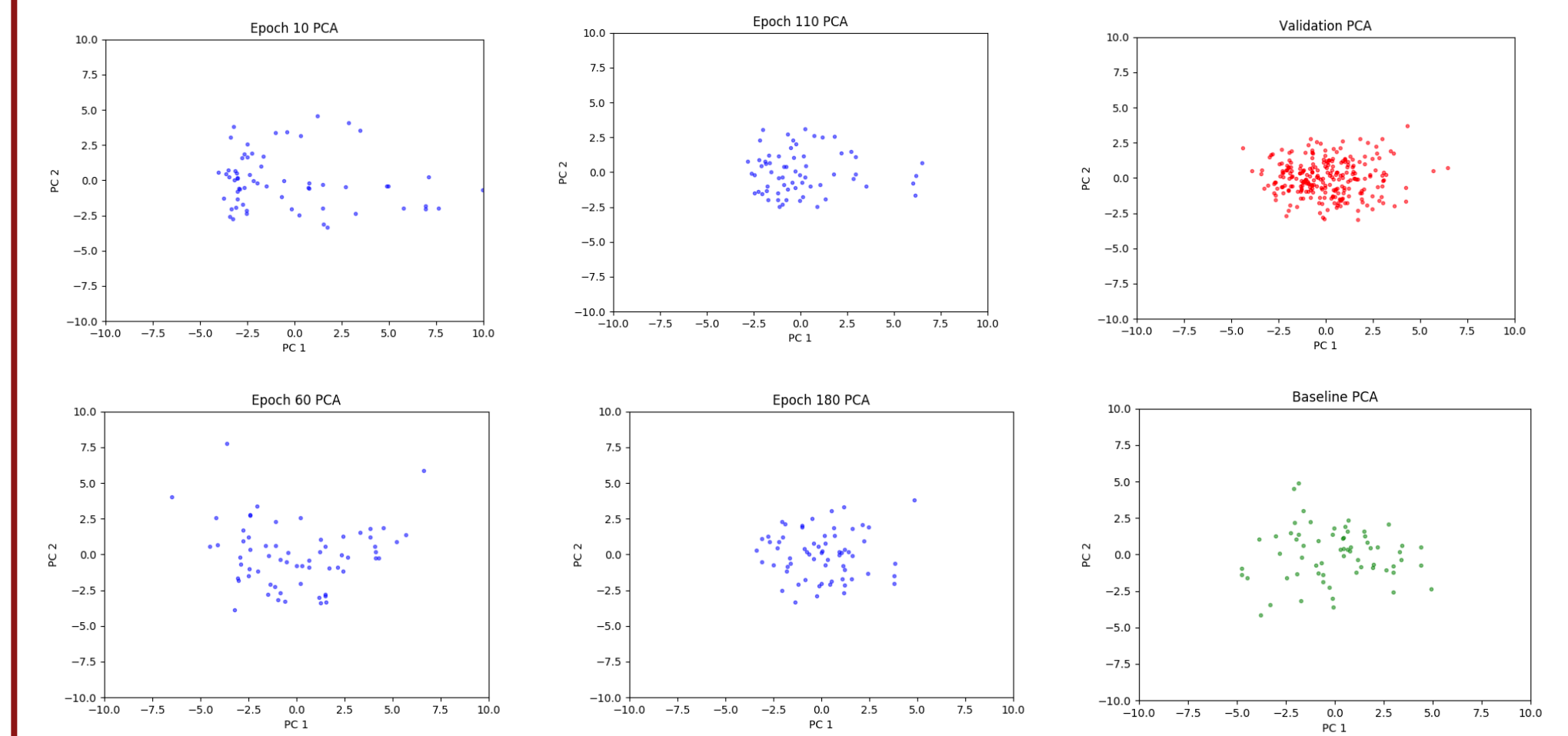
**Generator network architecture**  
Note the inclusion of Virtual Batch Normalization to optimize neural networks.

## Power Spectrum

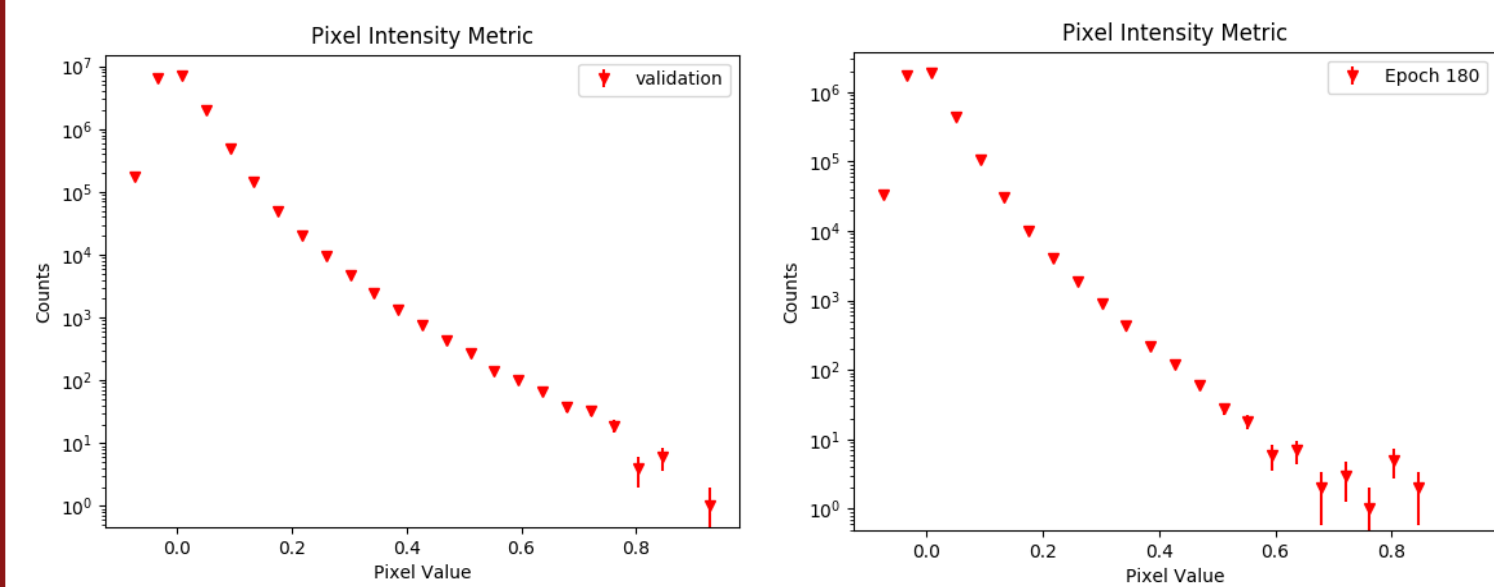
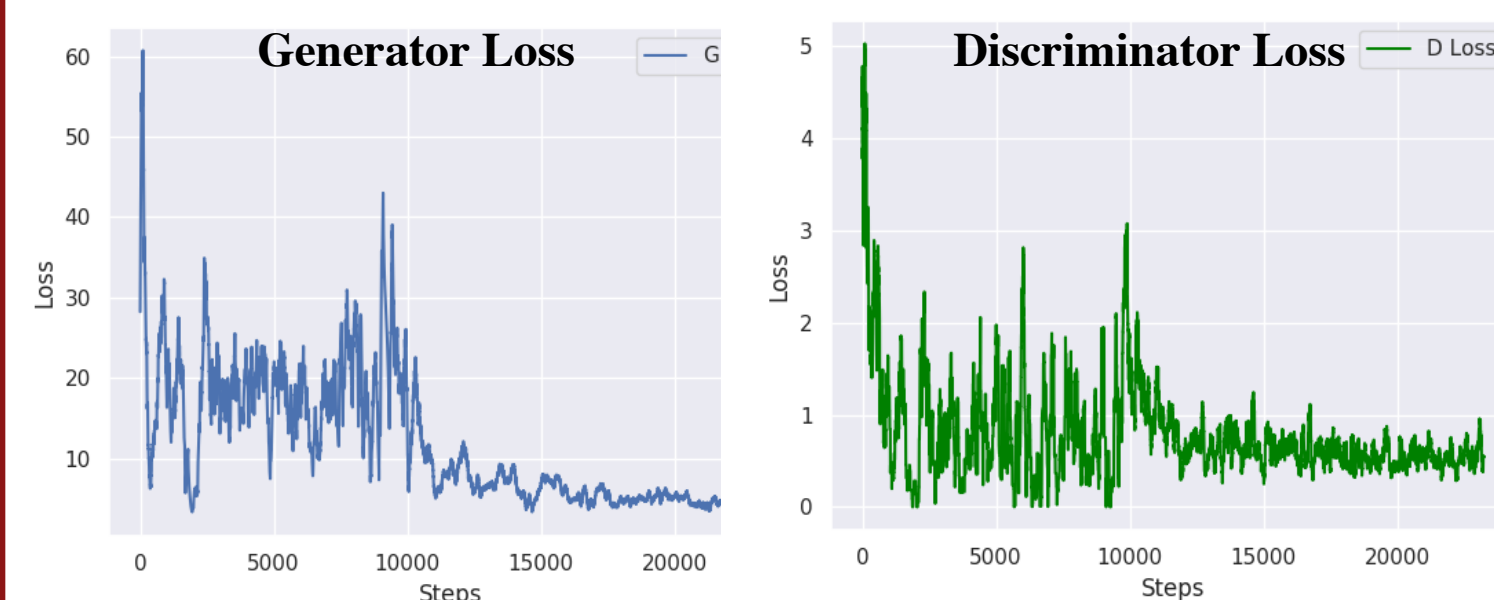


**Power Spectrum**  
A measure of correlation in gravitational lensing at different distances, evaluated at 248 Fourier modes.

## Principal Components Analysis

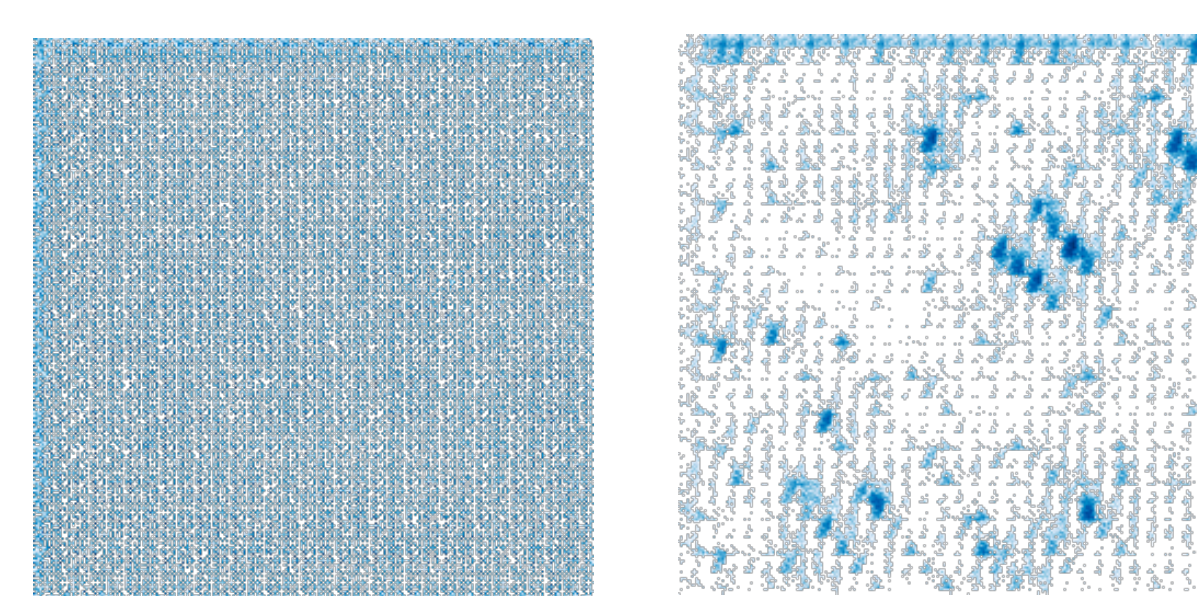


## Plots



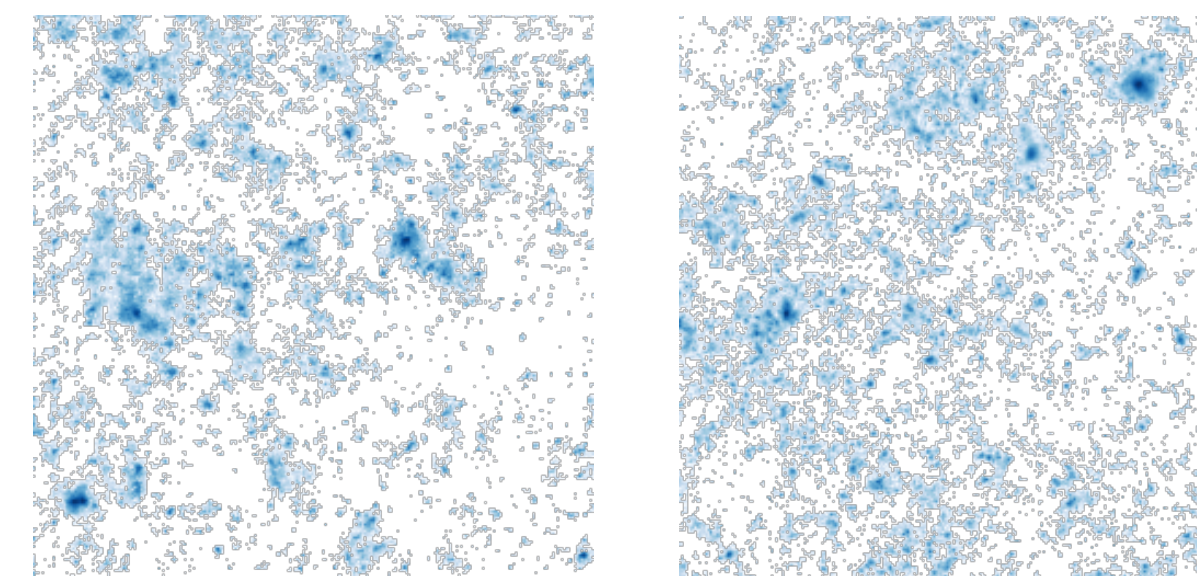
Generated pixel intensity metrics for validation (right) and generator model output (left)

## Generated Images



GeoGAN Epoch 5

GeoGAN Epoch 80



GeoGAN Epoch 185

Sample Baseline Image

## Summary

- GeoGAN(normal + relativistic hybrid) converges to similar test statistics as baseline in far less time (~ 23.75 hours) than research paper (~4 days).
- No observed mode collapse behavior, which was a challenge in baseline paper.
- Both GeoGAN and Relativistic GeoGAN showed similar levels of training stability.

### Future Work

- Explore more advanced metrics as test statistics, such as Minkowski functionals.
- Assess ability of GAN
- Extend approach from 2D to 3D mass simulations.
- Generate correlation matrices to analyze statistical independence of generated samples.

## References

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