



System Identification of Partial Differential Equations

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Objective

The goal of this project was to implement a system that takes in observed data and outputs a partial differential equation that describes the data. The system should

- Report results in terms interpretable by a human
- Be robust to noisy data
- Operate on small amounts of data

Data

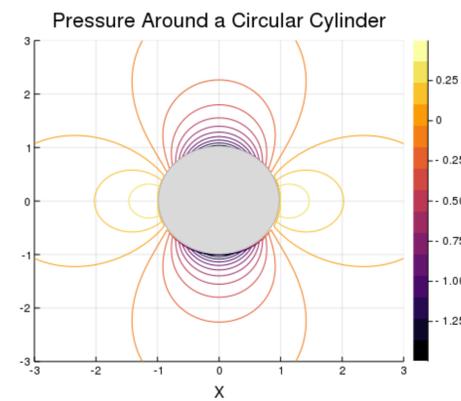
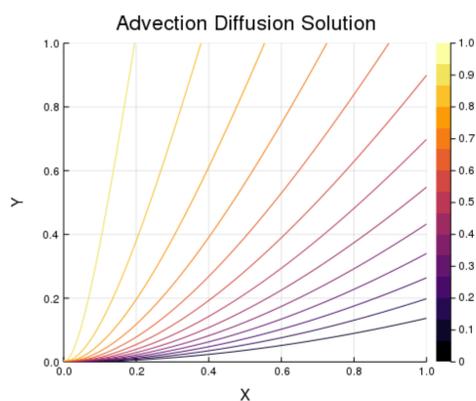
Synthetic noisy data was computed for two model processes from their exact solutions, with varying resolution and amount of noise

Advection-Diffusion Equation:

2D Euler Equations:

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} - v \frac{\partial u}{\partial x}$$

$$u_j \frac{\partial u_i}{\partial x_j} = - \frac{1}{\rho} \frac{\partial p}{\partial x_i}$$



Adding Noise

To add noise at a level η , add AGWN at each point

$$u_n = u + \epsilon \quad \epsilon \sim N(0, \eta \text{std}(u))$$

Noise was filtered using total variation denoising

Model and Feature Selection

Every PDE can be represented as a linear combination of nonlinear features: $\partial u / \partial t = \theta_i f_i(u)$

The candidate features are constructed using a domain specific grammar. Expressions are sampled with a preference for concise statements

Grammar:

$$\mathbb{R} \mapsto \partial \mathbb{R} / \partial x_i$$

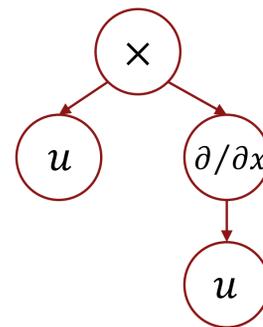
$$\mathbb{R} \mapsto \mathbb{R} \times \mathbb{R}$$

$$\mathbb{R} \mapsto \mathbb{R} / \mathbb{R}$$

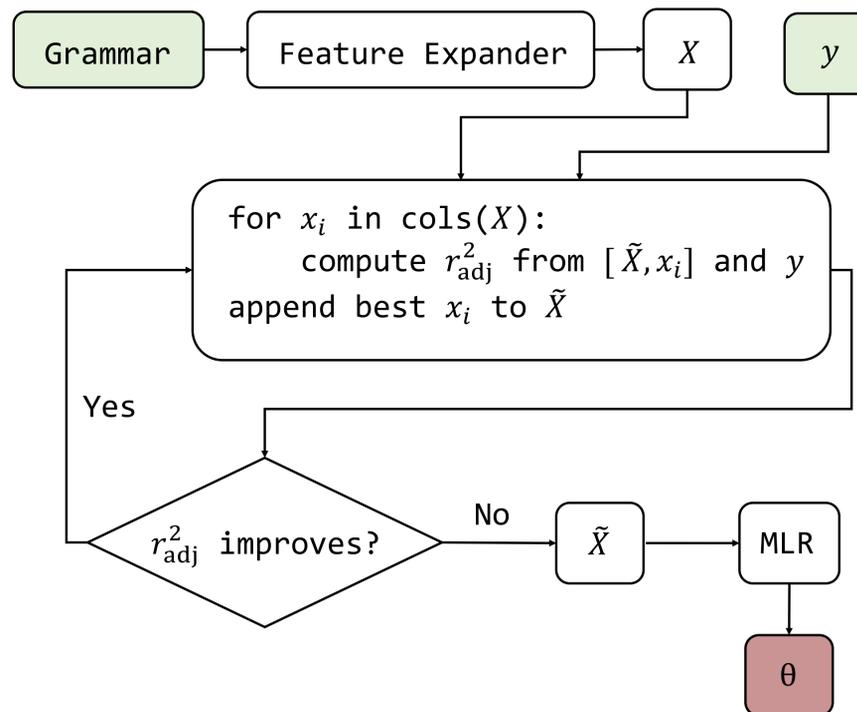
$$\mathbb{R} \mapsto \sqrt{|\mathbb{R}|}$$

$$\mathbb{R} \mapsto u_i \mid p$$

Sample Expression: $u \times \partial u / \partial x$



Feature Search Algorithm



Results

| Points (1D) | 100 | 50 | 15 | 5 |
|-------------|---|---|---|---|
| Adv-Diff | $D_{err} = 0.03\%$, $v_{err} = 0.03\%$ | $D_{err} = 0.08\%$, $v_{err} = 0.05\%$ | $D_{err} = 0.7\%$, $v_{err} = 0.3\%$ | $D_{err} = 7\%$, $v_{err} = 3\%$ |
| Euler | $\rho_{err} = 0.001\%$, $R_{err} = 0.002\%$ | $\rho_{err} = 0.005\%$, $R_{err} = 0.006\%$ | $\rho_{err} = 0.06\%$, $R_{err} = 0.06\%$ | $\rho_{err} = 0.6\%$, $R_{err} = 0.6\%$ |
| Noise | 1% | 5% | 15% | 50% |
| Adv-Diff | $D_{err} = 13\%$, $v_{err} = 7\%$ | $D_{err} = 14\%$, $v_{err} = 7\%$ | $D_{err} = 24\%$, $v_{err} = 5\%$ | $D_{err} = 70\%$, $v_{err} = .5\%$ |
| Euler | $\rho_{err} = 0.3\%$, $R_{err} = 2\%$ | $\rho_{err} = 0.1\%$, $R_{err} = 7.4\%$ | N/A | N/A |

Correct Identification (Green), Correct process didn't have highest r_{adj}^2 (Yellow), Not Identified (Red)

Discussion

The system successfully identifies the model processes with sufficient data. The system is robust to noise for the 1D process while the 2D process performed worse. Both processes were identified in the low-data limit with only moderate parameter error.

Future Work

- Improve feature search algorithm to include stochasticity through genetic algorithms
- Check robustness to different types of noise
- Apply to real world data of fluid flows

References

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