

Generating Video from Images

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Introduction

- **The problem:** Generate realistic videos from a given initial and final image.
- **The challenge:** Dimension of space of possible videos is frames \times height \times width \times colors. Very large even for short, low-resolution videos.
- **Approaches:** Conditional variational autoencoders (CVAEs) and conditional generative adversarial networks (CGANs), using deep convolutional neural networks (CNNs).

Dataset

- 'Moments in Time' [1]: 1,000,000 short videos, divided into 339 categories.
- Selected two categories: "Erupting" and "Skiing".
- Downsized to 30 frames, 64×64 pixels each frame

CVAE

- Training Objective:

$$\min \mathbb{E}_{x \sim p(x)} \{ D_{KL}[\mathcal{N}(\mu(x), \Sigma(x)) \| \mathcal{N}(0, I)] + \lambda_1 \|x - g_\theta(z)\|_2^2 + \lambda_2 (\|c(g_\theta(z)) - c(x)\|_2^2) \} \quad (1)$$

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$$z_{\text{total}} = z_{\text{video}} + z_{\text{first frame}} + z_{\text{last frame}} = 600 + 1000 + 1000$$

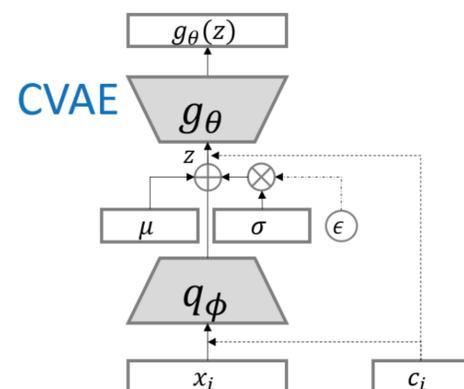


Figure: Training Video: x_i ; Initial/Final frames: c_i ; Generated Video: $g_\theta(z)$. Figure taken from [2].

Baseline Model

- Linear interpolation between initial and final image.

CGAN

- Training Objective:

$$\min_{w_G} \max_{w_D} \mathbb{E}_{x \sim p_x(x)} [\log D(x; w_D)] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(G(z; w_G); w_D))] + \mathbb{E}_{x \sim p_x(x)} [\lambda \|c(G(z; w_G)) - c(x)\|_2^2] \quad (2)$$

CGAN (cont.)

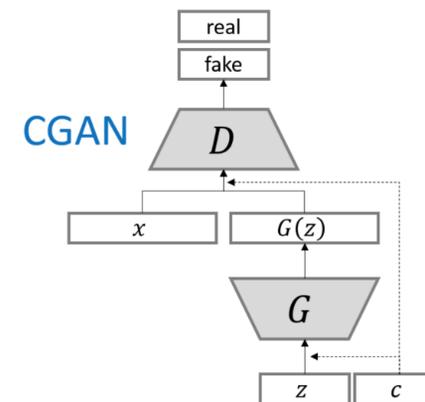


Figure: Training Video: x_i ; Initial/Final frames: c_i . Figure taken from [2].

Results and Evaluations

- Used Adam optimizer. Used "one-sided label smoothing" for CGAN.
- For "erupting": CVAE trained on 2000 videos, CGAN trained on 120 videos.
- For "skiing": CVAE trained on 1800 videos.
- Qualitative metric: Look at Videos!
- Quantitative metric: L_2 distance between generated and real videos (test set of 100 videos)

L_2 distance	Interpolation	CVAE	CGAN
Erupting	62 ± 58	180 ± 110	223 ± 96
Skiing	153 ± 89	197 ± 80	N/A

Future

- More time and GPU resources to train on larger datasets, and more carefully tune the hyperparameters.
- Use deeper and more complex architectures, e.g. recurrent neural networks (RNNs).

References

- [1] Mathew Monfort, Alex Andonian, Bolei Zhou, Kandan Ramakrishnan, Sarah Adel Bargal, Yan Yan, Lisa Brown, Quanfu Fan, Dan Gutfreund, Carl Vondrick, et al. Moments in time dataset: one million videos for event understanding. *IEEE transactions on pattern analysis and machine intelligence*, 2019.
- [2] Tensorflow generative model collections. <https://github.com/hwalsuklee/tensorflow-generative-model-collections/>.

Results (See our live demos!)



Figure: Examples of videos generated given an initial frame and a final frame. We used interpolation (our baseline), a trained CVAE, and a trained GAN.