

Motivation and Overview

- WFI: Detector system on Athena (an satellite observatory)
- **Purpose:** Distinguish between particles (protons) and X-ray photons. Eliminate particle background.
- Input: 500 by 500 gray scale image
- Output: 500 by 500 gray scale image

Data

- GEANT4: Particle simulation database [1]
- **SIXTE:** X-ray photon simulation database [2]







Figure: Typical X-ray Photon patterns







Figure: Typical Particle patterns







Figure: Train samples for the neural network

Reducing the ATHENA WFI background

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Models

First Step: DBSCAN [3] (Unsupervised Learning)

- Core point: A point that has at least minPts neighbor points within its ϵ radius.
- Border point: A point within the ϵ radius of a core point but has less than minPts other points within its own ϵ radius.
- Noise point: A point that is neither a core point or a border point.

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Experiment



1000 test samples, averaged error: 0.028

Figure: The left panel shows the image before processing, the right panel shows the image after processing.



econd Step: No	eural Network [4]
Preprocessing:	Heaviside step function $\mathcal{H}(x)$

• First Layer: Flatten Layer. $2d \rightarrow 1d$ • Second Layer: Fully Connected Layer. 256 Nodes. Activation: Relu

Last Layer: Fully Connected Layer. 1 Node. Activation: Sigmoid

$$a^{[1]} = max\{0, W^{[1]T}x_{flat}\}$$
(1)

$$p(y=1) = \frac{1}{1 + exp(-W^{[2]T}a^{[1]})}$$
(2)

The energy deposit of a particle is most probably much higher than that of a X-ray photon. The step function preprocessing tremendously improves the accuracy of the neural network, which suggests that **shape** is the key feature for the network to distinguish between particles and photons. In contrast, most existing works use classical algorithms that pay more attention to the **energy value** of pixels to distinguish [5].

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Discussions

Future Work

• Run the algorithm on real dataset • Analyze overlapping photon and particles.

References

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