

Finish Factor Analysis
PCA

A little behind our planned pace

But well within budget!

PLEASE KEEP QUESTIONS COMING

Factor Analysis Recap

$$x^{(1)}, \dots, x^{(n)} \in \mathbb{R}^d$$

Recall: Many fewer points than dimensions " $n \ll d$ "

think about: 1000 sensors measured for some small # of days

Key Idea: Latent structure in r.v. (constrains degree of freedom)

Recall Likelihood function

$$l(\mu, \Sigma) = \sum_{i=1}^n \log \frac{1}{2\pi |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (x^{(i)} - \mu)^T \Sigma^{-1} (x^{(i)} - \mu) \right\}$$

$$= \sum_{i=1}^n \left(-\frac{1}{2} (x^{(i)} - \mu)^T \Sigma^{-1} (x^{(i)} - \mu) - \log 2\pi |\Sigma|^{1/2} \right)$$

Here equivalent to max at

$$g(\mu, \Sigma) = \sum_{i=1}^n (x^{(i)} - \mu)^T \Sigma^{-1} (x^{(i)} - \mu) + \log |\Sigma| + \log 2\pi$$

WE'LL REASON ABOUT STRUCTURE IN Σ

Recall: If $\text{rank}(\Sigma) \leq n < d$, many problems: Σ^{-1} is not defined

$$|\Sigma| = 0$$

Estimate: of Σ is full rank, easy to estimate μ .

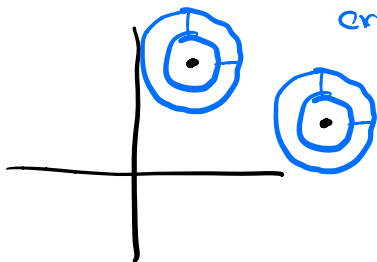
$$\nabla_{\mu} g(\mu, \Sigma) = 2 \sum_{i=1}^n \sum^{-1} (x^{(i)} - \mu) = 0 \quad (\text{CRITICAL POINTS})$$

$$\Leftrightarrow \sum_{i=1}^n \left(\sum_{i=1}^n (x^{(i)} - \mu) \right) = 0 \quad (\text{full rank})$$

$$\Rightarrow \mu = \frac{1}{n} \sum_{i=1}^n x^{(i)} \quad \text{ESTIMATE } \mu$$

$\therefore \mu$ IS EASY TO ESTIMATE WHEN Σ IS FULL RANK

Building Block 1 $\hat{\Sigma} = \sigma^2 I$ σ^2 IS JUST A SCALAR



CIRCULAR COVARIANCE

How many free parameters?

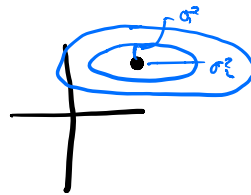
$\Rightarrow 1$ IN $\hat{\Sigma}$ (σ^2)

LAST TIME $\sigma^2 = \frac{1}{nd} \sum_{i=1}^n \|x^{(i)} - \mu\|^2$

ESTIMATE σ^2 BY SUBTRACTING MEAN, SQUARING VALUES

Building Block #2

$$\hat{\Sigma} = \begin{bmatrix} \sigma_1^2 & & 0 \\ & \dots & \\ 0 & & \sigma_n^2 \end{bmatrix}$$



AXIS ALIGNED

$$g(\mu, \hat{\Sigma}) = \sum_{i=1}^n (x^{(i)} - \mu)^T \hat{\Sigma}^{-1} (x^{(i)} - \mu) + \log |\hat{\Sigma}|$$

$$|\hat{\Sigma}| = \prod_{j=1}^d \sigma_j^2$$

$$(\hat{\Sigma} = \sigma_j^2) = \sum_{i=1}^n \sum_{j=1}^d z_j^{-1} (x_j^{(i)} - \mu_j)^2 + \log z_j$$

Decouples INTO d PROBLEMS.

$$\text{Fix } j \quad \sum_{i=1}^n z_j^{-1} (x_j^{(i)} - \mu_j)^2 + \log z_j$$

$$\sigma_j^2 = \frac{1}{n} \sum_{i=1}^n (x_j^{(i)} - \mu_j)^2 \quad \text{1d GAUSSIANS}$$

∴ if we assume this axis-aligned structure, we can also fit its components

OUR FACTOR MODEL

PARAMETERS

$$\boxed{\text{FIT}} \begin{cases} \mu \in \mathbb{R}^d & \text{SCD "small dim"} \\ \Lambda \in \mathbb{R}^{d \times s} \\ \Phi \in \mathbb{R}^{d \times d} \text{ - DIAGONAL MATRIX} \end{cases}$$

MODEL $P(x, z) = P(x|z)P(z)$ z IS LATENT VARIABLE

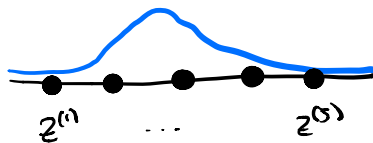
$$z \sim N(0, I) \in \mathbb{R}^s \text{ for SCD}$$

$$x = \underbrace{\mu}_{\text{MEAN}} + \underbrace{\Lambda z + \epsilon}_{\text{MAP FROM SMALL DIM S \& HIGH DIM}} \quad \text{OR } x \sim N(\mu + \Lambda z, \Phi)$$

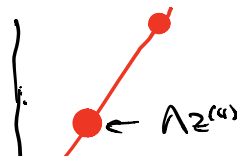
$$\epsilon \sim N(0, \Phi) \text{ NOISY.}$$

EX: $d=2, s=1, n=5 : x = \mu + \Lambda z + \epsilon$

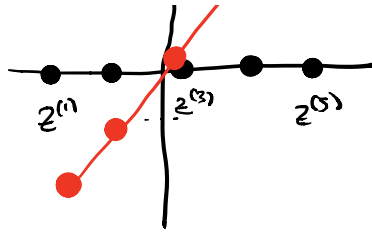
1. GENERATE $z^{(1)}, \dots, z^{(5)}$ FROM $N(0, 1)$



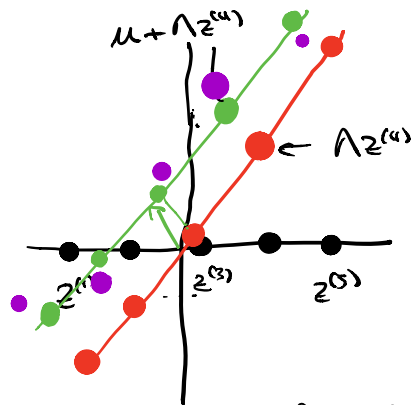
2. $\Lambda = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$



$$\Lambda z$$



3. Add μ



$$x = \mu + \Lambda z + \epsilon$$

finally our data points which are dimensional

Model is over: Small dim \rightarrow large dim

TECHNICAL TOOLS Block Gaussians

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad x_1 \in \mathbb{R}^{d_1} \quad x_2 \in \mathbb{R}^{d_2} \quad x \in \mathbb{R}^{d_1+d_2}$$

$$\Sigma = \begin{bmatrix} \hat{\Sigma}_{11} & \hat{\Sigma}_{12} \\ \hat{\Sigma}_{21} & \hat{\Sigma}_{22} \end{bmatrix} \begin{matrix} | \\ | \end{matrix} \begin{matrix} d_1 \\ d_2 \end{matrix} \quad \hat{\Sigma}_{ij} \in \mathbb{R}^{d_i \times d_j} \quad i, j \in \{1, 2\}$$

FACT 1: $P(x_1) = \int_{x_2} P(x_1, x_2)$ MARGINALIZATION
 For GAUSSIANS, $P(x_1) = \mathcal{N}(\mu_{11}, \hat{\Sigma}_{11})$ GAUSSIAN

FACT 2: $P(x_1 | x_2) \sim \mathcal{N}(\mu_{1|2}, \hat{\Sigma}_{1|2})$ CONDITIONAL
 $\mu_{1|2} = \mu_{11} + \hat{\Sigma}_{12} \hat{\Sigma}_{22}^{-1} (x_2 - \mu_{21})$

MATRIX INVERSION

lemma

$$\hat{\Sigma}_{1|2} = \hat{\Sigma}_{11} - \hat{\Sigma}_{12} \hat{\Sigma}_{22}^{-1} \hat{\Sigma}_{21}$$

Summary: learned about block notation

‡ we say Gaussians are closed under
marginalization ‡ conditioning.

FACTOR ANALYSIS GIVE

$$x = \mu + \Lambda z + \epsilon$$

$$\begin{pmatrix} z \\ x \end{pmatrix} \sim N \left(\begin{pmatrix} 0 \\ \mu \end{pmatrix}, \hat{\Sigma} \right) \quad \text{SINCE } \mathbb{E}[z] = 0 \\ \mathbb{E}[x] = \mu$$

$$\hat{\Sigma}_{11} = \mathbb{E}[z z^T] = \mathbf{I} \quad (z \sim N(0, \mathbf{I}))$$

$$\hat{\Sigma}_{12} = \mathbb{E}[z(x-\mu)^T] = \mathbb{E}[z z^T \Lambda^T] + \mathbb{E}[\cancel{z \epsilon^T}] \\ = \Lambda^T$$

$$\hat{\Sigma}_{21} = \hat{\Sigma}_{12}^T \quad (\hat{\Sigma} \text{ is symmetric})$$

$$\begin{aligned} \hat{\Sigma}_{22} &= \mathbb{E}[(x-\mu)(x-\mu)^T] \\ &= \mathbb{E}[(\Lambda z + \epsilon)(\Lambda z + \epsilon)^T] \\ &= \mathbb{E}[\Lambda z z^T \Lambda^T] + \mathbb{E}[\epsilon \epsilon^T] \\ &= \Lambda \Lambda^T + \mathbf{\Sigma}_{\epsilon} \end{aligned}$$

$$\hat{\Sigma} = \begin{bmatrix} \mathbf{I} & \Lambda^T \\ \Lambda \Lambda^T + \mathbf{\Sigma}_{\epsilon} & \end{bmatrix} \quad \text{Diagonal matrix.}$$

$$L \sim \Lambda \Lambda^T + \frac{1}{\Phi}$$

EM Algorithm?

E-STEP: $Q_i(z) = P(z^{(i)} | x^{(i)}, \theta)$ - USE CONDITIONAL

M-STEP: WE KNOW HOW TO ESTIMATE.

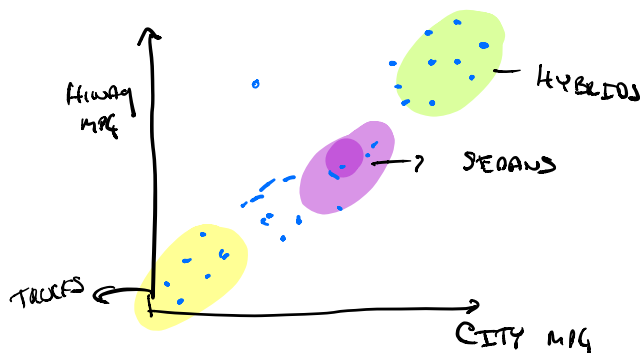
Summary:

- WE SAID THAT EM CAPTURED GMM
- WE LEARNED FACTOR ANALYSIS (FA)
- WE SAID THAT ESTIMATES PARAMETERS OF FA WITH EM

PCA: PRINCIPAL COMPONENT ANALYSIS

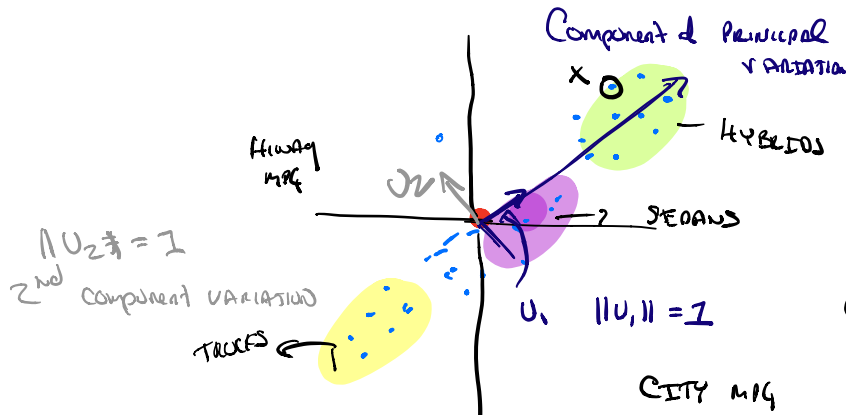
STRUCTURE	Prob.	NON-Prob.
"CLUSTER"	GMM FACTOR	K-MEANS
"SUBSPACE"	FACTOR ANALYSIS	PCA

EX: GIVEN PAIRS ABOUT CARS (HIGHWAY MPG, CITY MPG)



Question: "Good mix"

$$x^{(1)} \dots x^{(n)} \in \mathbb{R}^d$$



CENTER DATA

$$\mu = \frac{1}{n} \sum_i x^{(i)}$$

$$x^{(i)} \mapsto x^{(i)} - \mu$$

$$U_1 \cdot U_2 = 0$$

$$U_i \cdot U_j = \delta_{ij} \text{ (Orthonormal Basis)}$$

U_1 IS "How good is mix"

U_2 IS "Difference Hiway and city"

$$x = \alpha_1 U_1 + \alpha_2 U_2$$

↳ Keeping this one term

$x^{(i)}$ keep around $\alpha_1^{(i)}$ AS ONE NUMBER INSTEAD of 2.

What we'll think ABOUT IS WHEN WE HAVE 1000s of directions

AND WE WANT TO find a few important ones

$\mathbb{R}^{1000} \rightarrow \mathbb{R}^{10}$ or \mathbb{R}^2 for visualization.

$$U_i \text{ s.t. } \|U_i\| = 1 \text{ AND } U_i \cdot U_j = \delta_{ij} \quad (i=1..n \quad U_i \in \mathbb{R}^n)$$

$$x = \sum \alpha_i U_i \text{ (WRITE IN A BASIS)}$$